

Problem Solution #6

Problem 1

Poisson's equation: $\nabla^2 \vec{A} = -\mu_0 \vec{J}$

$$\nabla^2 \vec{A} = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \vec{A} = \hat{a}_x \nabla^2 A_x + \hat{a}_y \nabla^2 A_y + \hat{a}_z \nabla^2 A_z$$

Here $\vec{A} = -\frac{\mu_0 J_0}{4} (x^2 + y^2) \hat{a}_z$ so

$$\nabla^2 \vec{A} = \hat{a}_z \nabla^2 A_z = \hat{a}_z \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left[-\frac{\mu_0 J_0}{4} (x^2 + y^2) \right] = \hat{a}_z \left(-\frac{\mu_0 J_0}{2} - \frac{\mu_0 J_0}{2} \right) = -\mu_0 J_0 \hat{a}_z = -\mu_0 \vec{J}$$

$$\vec{B} = \nabla \times \vec{A} = \begin{pmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & A \end{pmatrix} = \frac{\partial A}{\partial y} \hat{i} - \frac{\partial A}{\partial x} \hat{j} = -\frac{\mu_0 J_0}{2} y \hat{i} + \frac{\mu_0 J_0}{2} x \hat{j} = \boxed{\frac{\mu_0 J_0}{2} (-y \hat{i} + x \hat{j})}$$

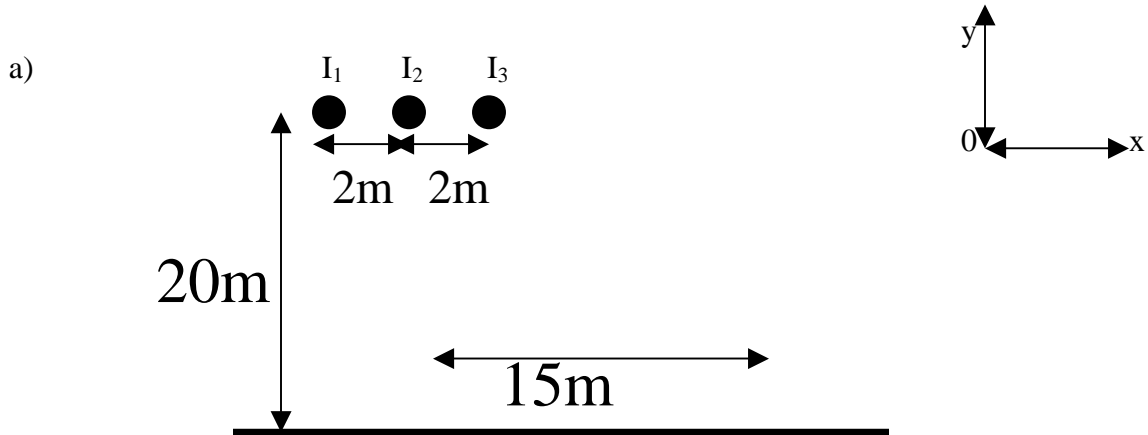
$$\vec{B} = \mu_0 \vec{H} \Rightarrow \vec{H} = \frac{\vec{B}}{\mu_0} = \boxed{\frac{J_0}{2} (-y \hat{i} + x \hat{j})}$$

Ampere's law: $\oint_c \vec{H} \cdot d\vec{l} = I$

$$\oint_c \vec{H} \cdot d\vec{l} = \int \nabla \times \vec{H} \cdot d\vec{s} = \int \frac{J_0}{2} \begin{pmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y & x & 0 \end{pmatrix} \cdot \hat{k} ds = \int \frac{J_0}{2} (1\hat{k} + 1\hat{k}) \cdot \hat{k} ds = \int J_0 \hat{k} \cdot \hat{k} ds = \int \vec{J} \cdot \hat{k} ds = I$$

or just try to confirm $\nabla \times \vec{H} = \vec{J}$

Problem 2



$$\oint_c \vec{H} \cdot d\vec{l} = I \Rightarrow \vec{H} = \frac{I}{2\pi r} \hat{\phi}$$

$$\begin{aligned}
H_{1x} &= H_1 \frac{20}{r} = \frac{20I_1}{2\pi r^2} = -\frac{20 \times 250}{2\pi(17^2 + 20^2)} & H_{1y} &= H_1 \frac{17}{r} = \frac{17I_1}{2\pi r^2} = -\frac{17 \times 250}{2\pi(17^2 + 20^2)} \\
H_{2x} &= H_2 \frac{20}{r} = \frac{20I_2}{2\pi r^2} = \frac{20 \times 500}{2\pi(15^2 + 20^2)} & H_{2y} &= H_2 \frac{15}{r} = \frac{15I_2}{2\pi r^2} = \frac{15 \times 250}{2\pi(15^2 + 20^2)} \\
H_{3x} &= H_3 \frac{20}{r} = \frac{20I_3}{2\pi r^2} = -\frac{20 \times 250}{2\pi(13^2 + 20^2)} & H_{3y} &= H_3 \frac{13}{r} = \frac{13I_3}{2\pi r^2} = -\frac{13 \times 250}{2\pi(13^2 + 20^2)} \\
H_x &= H_{1x} + H_{2x} + H_{3x} \approx \boxed{-0.007 \text{ A/m}} & H_y &= H_{1y} + H_{2y} + H_{3y} \approx \boxed{0.019 \text{ A/m}} \\
\vec{H} &= \boxed{-0.007\hat{x} + 0.019\hat{y} \text{ (A/m)}}
\end{aligned}$$

$$\text{b) } \vec{H} = \frac{Ia^2}{2(a^2 + z^2)^{3/2}} \hat{z} = \frac{1 \times 0.02^2}{2(0.02^2 + 0.5^2)^{3/2}} \hat{z} \approx 1.6\hat{z} \text{ (mA/m)}$$

Problem 3

Boundary condition: $\mu_1 H_{1n} = \mu_2 H_{2n}$ and $H_{1t} = H_{2t}$

Then $\mu_1 H_1 \cos \theta_1 = \mu_2 H_2 \cos \theta_2$, $\mu_2 H_2 \cos \theta_2 = \mu_3 H_3 \cos \theta_3$, and

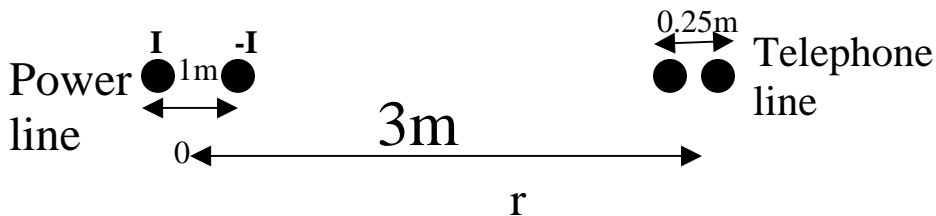
$$H_1 \sin \theta_1 = H_2 \sin \theta_2, \quad H_2 \sin \theta_2 = H_3 \sin \theta_3$$

$$\text{so } \theta_3 = \tan^{-1} \left(\frac{\mu_1 \tan \theta_1}{\mu_3} \right)$$

These show that the angle θ_3 is independent of μ_2 .

Problem 4

Set the center of the power line as the origin,



$$\oint_c \vec{B} \cdot d\vec{l} = \mu_0 I \Rightarrow \vec{B} = \frac{\mu_0 I}{2\pi r} \hat{\phi}$$

$$B_+ = \frac{\mu_0 I}{2\pi(0.5 + r)} \quad B_- = -\frac{\mu_0 I}{2\pi(r - 0.5)}$$

$$\Phi = \int \vec{B} \cdot d\vec{s}$$

$$\Phi = \frac{I\mu_0}{2\pi} \int_{3-\frac{0.25}{2}}^{3+\frac{0.25}{2}} \left(\frac{1}{r+0.5} - \frac{1}{r-0.5} \right) dr$$

$$= \frac{I\mu_0}{2\pi} \left\{ \ln(r+0.5) - \ln(r-0.5) \right\} \Big|_{2.875}^{3.125} \approx \boxed{-5.72 \times 10^{-7} \text{ Wb}}$$