



# Fields and Waves

## Lesson 1.3

### VECTOR CALCULUS - Line Integrals, Curl & Gradient



## DIFFERENTIAL LENGTHS

Representation of differential length  $d\vec{l}$  in coordinate systems:

rectangular  $d\vec{l} = dx \cdot \hat{a}_x + dy \cdot \hat{a}_y + dz \cdot \hat{a}_z$

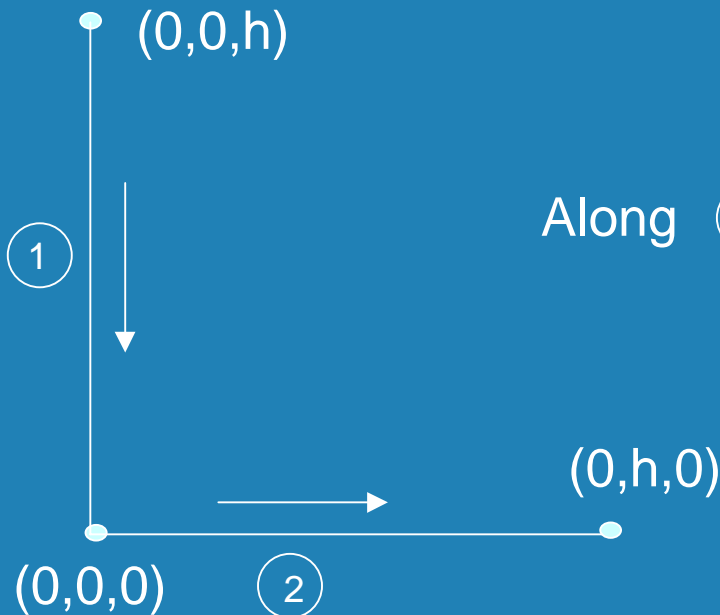
cylindrical  $d\vec{l} = dr \cdot \hat{a}_r + rd\phi \cdot \hat{a}_\phi + dz \cdot \hat{a}_z$

spherical  $d\vec{l} = dr \cdot \hat{a}_r + rd\theta \cdot \hat{a}_\theta + r \sin \theta d\phi \cdot \hat{a}_\phi$

# LINE INTEGRALS

## EXAMPLE: GRAVITY

Define Work or Energy Change:



Along ①

$$W = \int \vec{F} \cdot d\vec{l}$$

$$= \int_1 \vec{F} \cdot d\vec{l} + \int_2 \vec{F} \cdot d\vec{l}$$

$$d\vec{l} = dz \cdot \hat{a}_z \quad (dx \text{ \& } dy = 0)$$

$$\vec{F} \cdot d\vec{l} = -mg \, dz$$

$$\int \vec{F} \cdot d\vec{l} = -\int_h^0 mg \, dz = mgh$$

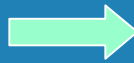
# LINE INTEGRALS

Along ②

$$d\vec{l} = dy \cdot \hat{a}_y$$

(dx & dz = 0)

$$\vec{F} \cdot d\vec{l} = -0 \cdot dy$$



Vectors are perpendicular  
to each other

$$\int \vec{F} \cdot d\vec{l} = -\int_0^h 0 \cdot dy = 0$$

Final Integration:  $W = \int \vec{F} \cdot d\vec{l} \Rightarrow W = mgh$

# LINE INTEGRALS

Note: For the first integral, DON'T use  $d\vec{l} = -dz \cdot \hat{a}_z$

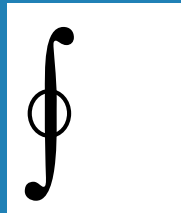
Negative Sign comes in through integration limits

For PROBLEM 1a - use Cylindrical Coordinates:

Differential  
Line Element

$$d\vec{l} = dr \cdot \hat{a}_r + rd\phi \cdot \hat{a}_\phi + dz \cdot \hat{a}_z$$

NOTATION:



Implies a CLOSED LOOP Integral

# LINE INTEGRALS - ROTATION or CURL

$$\oint \vec{A} \cdot d\vec{l}$$

Measures Rotation or Curl

For example in Fluid Flow:

$$\oint \vec{v} \cdot d\vec{l} \neq 0$$

Means ROTATION or “EDDY CURRENTS”

$$\oint \vec{v} \cdot d\vec{l}$$

Integral is performed over a large scale (global)

However,

$$\nabla \times \vec{v}$$

, the “CURL of  $v$ ” is a local or a POINT measurement of the same property

## ROTATION or CURL

NOTATION:  $\nabla \times \vec{v}$  is NOT a CROSS-PRODUCT

Result of this operation is a VECTOR

*Note: We will not go through the derivation of the connection between*

$$\oint \vec{A} \cdot d\vec{l} \iff \nabla \times \vec{A}$$

More important that you understand how to apply formulations correctly

To calculate CURL, use formulas in the TEXT

## ROTATION or CURL

Example: SPHERICAL COORDINATES

$$\vec{A} = \frac{c}{r^2} \cdot \sin \theta \cdot \hat{a}_\theta$$

$$A_\theta$$



$$\vec{A} = A_\theta \cdot \hat{a}_\theta$$

We quickly note that:

$$A_r = A_\phi = 0$$



## ROTATION or CURL

$\nabla \times \vec{A}$  , has 6 terms - we need to evaluate each separately

Start with last two terms that have  $\phi$  - dependence:

$$\hat{a}_\phi \cdot \frac{1}{r} \left[ \frac{\partial}{\partial r} (rA_\theta) - \frac{\partial A_r}{\partial \theta} \right] = \hat{a}_\phi \cdot \frac{1}{r} \frac{\partial}{\partial r} \left( \frac{c \cdot \sin \theta}{r} \right)$$

0

$$\begin{aligned} &= \hat{a}_\phi \cdot \frac{c \sin \theta}{r^2} \cdot \left( -\frac{1}{r^2} \right) \\ &= \frac{-c \sin \theta}{r^3} \cdot \hat{a}_\phi \end{aligned}$$

## ROTATION or CURL

4 other terms include: two  $A_\phi$  terms and two  $A_r$  terms  0

Example:

$$\hat{a}_r \cdot \frac{1}{r \sin \theta} \left( -\frac{\partial A_\theta}{\partial \phi} \right) = 0, \text{ because } A_\theta \text{ has NO PHI DEPENDENCE}$$

THUS,

$$\nabla \times \vec{A} = -\frac{c \sin \theta}{r^3} \cdot \hat{a}_\phi$$

*Do Problem 1b and Problem 2*

# GRADIENT

GRADIENT measures CHANGE in a SCALAR FIELD

- the result is a VECTOR pointing in the direction of increase

For a Cartesian system:

$$\nabla f = \frac{\partial f}{\partial x} \cdot \hat{a}_x + \frac{\partial f}{\partial y} \cdot \hat{a}_y + \frac{\partial f}{\partial z} \cdot \hat{a}_z$$

Do Problems 3 and 4

You will find that  $\nabla \times \nabla f = 0$   
ALWAYS

IF  $\vec{F} = \nabla f$  , then  $\nabla \times \vec{F} = 0$  and  $\oint \vec{F} \cdot d\vec{l} = 0$